



Six Sigma Dimensional Control Frameworks for Safety-Critical Assemblies in Emerging Aviation Technologies

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Abstract— Safety-critical aerospace assemblies are produced under a narrower dimensional margin than conventional industrial systems. At the same time, digital manufacturing, composite structures, and hybrid joining routes increase the number of deviation pathways that can affect fit, load transfer, sealing, and long-term reliability. This article develops an analytical model of Six Sigma dimensional control for emerging aviation technologies. The study examines how recent research links tolerance allocation, metrology, digital twins, deviation-source modeling, and capability assurance in aerospace and adjacent high-precision assembly environments. The source base includes ten recent peer-reviewed studies published between 2022 and 2024. Comparative analysis, source analysis, conceptual synthesis, typologization, and analytical generalization were applied. The analytical section reconstructs a closed-loop control architecture, identifies the most stable implementation sequence, and formulates decision rules for process monitoring and intervention. The proposed framework can be used for early design screening, fixture planning, measurement planning, digital model calibration, and production-stage capability governance in safety-critical assembly programs.

Keywords— six sigma, dimensional control, aerospace assembly, digital twin, tolerance allocation, geometry assurance, metrology, assembly variation, capability control, safety-critical manufacturing.

I. INTRODUCTION

Safety-critical aerospace assemblies are exposed to a form of dimensional risk distinct from conventional tolerance management. A local deviation in a locating feature, a fixture point, or a compliant mating surface does not stay local for long. It moves through the assembly chain, changes the contact condition, alters the fit at downstream interfaces, and in severe cases affects sealing, aerodynamic contour, vibration behavior, or service reliability. Recent aerospace studies describe this shift directly. Current aerospace research treats dimensional control as a problem of deviation propagation, in-process observability, and

closed-loop correction within digital production environments.

This study develops an analytical framework for Six Sigma dimensional control in safety-critical assemblies used in emerging aviation technologies. To achieve this goal, three objectives are being solved. The first identifies the main deviation sources and control layers that structure dimensional governance in aerospace assembly. The second determines how metrology and digital twin environments convert static tolerance planning into a closed control cycle. The third formulates an implementation logic for selective tolerance tightening, capability verification,

and production-stage monitoring. The novelty of the article lies in combining recent studies of aerospace deviations, metrology-driven assembly simulation, and tolerance-cost research within a single six sigma framework for aviation use cases.

The working hypothesis states that Six Sigma dimensional control in aerospace assembly achieves practical value only when tolerance allocation, deviation prediction, measurement feedback, and intervention rules operate as a single closed architecture.

II. MATERIALS AND METHODS

The source corpus comprises 10 peer-reviewed studies published between 2022 and 2024. The selection logic followed three filters. First, each source had to address one of the following: aerospace assembly, aerospace-oriented digital twins, metrology-supported geometry assurance, or tolerance-cost control in high-precision mechanical assemblies. Second, the source had to contribute to at least one of the three research objectives fixed in the Introduction. Third, the set as a whole had to cover the full control chain, from deviation-source modeling to monitoring and capability governance. The final corpus covers five connected clusters: deviation accumulation in aircraft structures, metrology-supported virtual assembly, digital twin control for aerospace or precision assembly, tolerance-cost optimization, and geometry assurance under individualized or data-driven production conditions [1–10].

The study applies comparative analysis to align heterogeneous engineering studies within one control problem, source analysis to isolate transferable technical propositions, conceptual synthesis to reconstruct a closed-loop dimensional architecture, typologization to separate design, measurement, digital-model, and decision layers, and analytical generalization to translate literature findings into an implementation-ready framework for safety-critical aerospace assembly.

III. RESULTS

The first recurring finding concerns the source structure of dimensional risk. Recent aerospace

studies do not treat deviation as an isolated geometric error confined to a single part. Research on multi-level assembly of an aircraft rear fuselage frame models deviation as the combined result of manufacturing deviation, fixture positioning deviation, and assembly contact deviation, all of which interact during station-to-station transfer [9]. Work on fabricated aerospace assemblies with digital twins reaches a similar position from a different path. In-line manufacturing data and non-nominal welding simulation are used to individualize assembly operations, thereby reconstructing the effective geometry from actual part conditions [3]. The same logic applies in aero-engine casing research, where tolerance analysis is linked to performance instability [4]. The authors show that the control problem extends beyond isolated geometric variation. Engineers manage coupled deviation pathways.

That shift has immediate consequences for Six Sigma thinking. In aerospace assembly, sigma performance has to be interpreted through structural sensitivity, fixture influence, contact closure, and performance-critical interfaces. In the rear fuselage frame model, rigid and compliant deviations are treated differently because weakly rigid parts do not accumulate error in the same manner as rigid components [9]. In the aero-engine casing study, assembly tolerance is evaluated through its influence on dynamic performance instability, thereby tying dimensional governance to product behavior under operating conditions [4]. The practical implication is direct. A six sigma framework for aviation assemblies cannot be reduced to a late-stage capability calculation. It needs a prior map of structural sensitivity, fixture influence, contact closure, and performance-critical interfaces.

A second line of findings concerns measurement and virtual representation. The recent literature moves away from tolerance allocation as a one-time design act. A metrology-aided virtual approach for aeronautical product assembly uses measurement data to drive assembly simulation before final mating decisions are locked in [5]. A digital twin method for complex product assembly extends this logic by integrating virtual and physical information into a progressively deduced tolerance-allocation scheme designed for high-precision aerospace components [10]. A related study on digital twin-based quality management in aerospace assembly links process

disturbances, abnormality prediction, and cause identification within a single quality management environment [8]. The authors reach the same conclusion. Dimensional control becomes more reliable when the digital model is updated by the measured state of the physical assembly.

This transition from static planning to closed control is reinforced by research outside the narrow aerospace label but still inside precision assembly. Online geometry assurance through digital twin calibration treats control and calibration as connected tasks, with the virtual model corrected during the assembly process [6]. A broader review of digital twins in aircraft production and MRO argues for fit-for-purpose twins, which means that the twin gains industrial value when it is tied to a sharply bounded operational task such as assembly planning, quality assurance, or maintenance support [7]. A perspective on digital twins in mechanical and aerospace engineering reaches a similar conclusion and frames them as capability-driven constructs [2]. Read together, these studies clarify the architecture needed for six sigma dimensional control. The digital twin is the medium through which measurement, prediction, and intervention are connected.

The literature also clarifies where cost enters the control chain. Tolerance tightening remains expensive, and recent work does not treat that expense as an afterthought. One 2024 study estimates cost reduction by tolerance optimization and shows that allocation decisions shape manufacturing choices in measurable ways [1]. A 2023 cost-based optimization study in mechanical assemblies builds the same argument in a more general design setting and frames tolerance development as a balance between manufacturing cost, non-quality cost, and functional constraints [8]. In aerospace assembly, that balance becomes stricter because some constraints are non-negotiable. The aero-engine casing study links tolerance choices to final dynamic performance [4]. In such cases, it moves into a ranked decision structure, where performance-critical interfaces receive tighter control while secondary contributors are managed with wider bands.

A comparison of four studies sharpens this point. The aircraft rear fuselage study identifies multiple deviation sources and their transfer rules [9]. The metrology-aided aeronautical assembly study brings

measured geometry into the simulation loop [5]. The online geometry assurance study adds calibration and feedback control [6]. The 2024 data-driven tolerance-allocation study turns that closed loop into an explicit deduction mechanism for later-stage tolerance decisions [10]. The progression across these sources occupies a distinct layer of the same architecture. The first explains where deviations form and accumulate. The second captures the physical state before irreversible assembly steps. The third updates the twin and supports intervention. The fourth reallocates dimensional control based on real production evidence. Six sigma fits this sequence because sigma performance depends on all four layers.

Figure 1 condenses this result into a control chain reconstructed from the literature. It should be read as a closed architecture instead of a linear checklist.

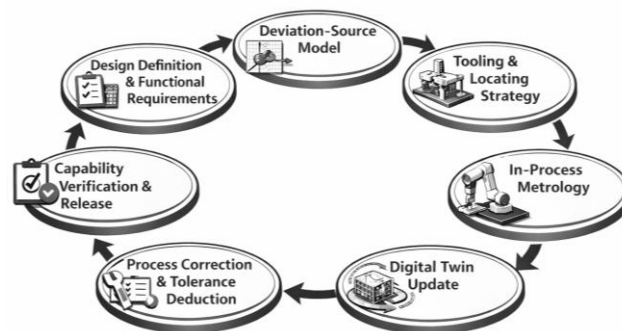


Fig. 1: Closed-loop architecture of six sigma dimensional control for safety-critical assemblies, adapted from [3; 5–7; 9; 10]

Recent studies call for early identification of dominant contributors, online observation of real geometry, calibration of the virtual model, and selective intervention in the small subset of variables that control assembly precision. In applied engineering language, that logic is close to the one hard-point sensitivity, selective tightening, and cost-aware robustness screening. The FISITA paper describes six sigma achievement through the identification of critical hard points, tolerance optimization in 3DCS, and controlled cost impact, reporting a 34% cost reduction under optimized tolerance tightening and noting that further reductions follow from relaxing non-critical hard points.

IV. DISCUSSION

The literature supports a closed-loop model of dimensional governance, but deployment fails when aerospace programs treat the loop as a stack of disconnected specialist tasks. Design engineers define tolerances. Tooling teams define locators. Metrology teams collect data. Quality teams calculate capability. Digital teams maintain the twin. This division of labor is manageable only as long as deviations remain small and local. Safety-critical assemblies operate under a

tighter margin. The same geometric disturbance touches fit, load path, surface continuity, sealing, and inspection planning. A working model has to assign each decision to a specific stage and bind it to a clear escalation rule.

Table 1 structures that sequence. The purpose of the table lies in separating the design-stage questions from the production-stage questions. Without that separation, organizations tend to tighten tolerances too late, or measure the wrong feature too early.

Table 1. Implementation logic for six sigma dimensional control in safety-critical aerospace assembly

Lifecycle stage	Primary decision	Dominant evidence	Release criterion	Main output
Concept definition	Identify safety-critical interfaces and failure-sensitive dimensions	Functional architecture, load paths, sealing and alignment requirements	Agreement on critical interface map	Initial control boundary
Detailed design	Rank deviation contributors and define tolerance priorities	GD&T scheme, interface sensitivity, compliance assumptions	Sensitivity-ranked tolerance plan	Targeted tolerance architecture
Tooling planning	Select locating and clamping logic with minimum amplification	Locator layout, access constraints, deformation risk, fixture repeatability	Approved locating strategy	Robust fixture concept
Pre-production validation	Check agreement between predicted and measured deviation behavior	Trial metrology, virtual assembly, early capability estimates	Acceptable prediction fidelity	Calibrated digital model
Serial production	Maintain capability at critical interfaces	In-process measurements, drift patterns, and correction history	Stable capability inside the release band	Controlled production state
Change management	Decide whether drift requires compensation or redesign	Recurring escapes, tooling wear, engineering changes, and twin mismatch	Escalation by source severity	Updated control baseline

The table points to a practical conclusion. Six sigma in aerospace assembly starts long before Cp or Cpk enters a dashboard. The decisive move occurs earlier, when the program identifies which dimensions govern function and which ones merely consume engineering attention. Once that distinction is made,

measurement planning becomes sharper and intervention becomes cheaper.

A second implementation problem concerns metrics. Many-dimensional dashboards collect everything that can be measured and still fail to support action. A usable control system separates symptom metrics from source metrics, and it distinguishes model

quality from process quality. Table 2 translates that requirement into a compact monitoring set.

Table 2. Monitoring metrics for closed-loop dimensional governance

Metric family	What is monitored	Operational meaning	Typical trigger
Interface metrics	Gap, flush, coaxiality, positional error, clearance spread	Direct evidence of assembly acceptability	Repeated proximity to the specification edge
Source metrics	Locator drift, fixture offset, clamp instability, local deformation	Probable origin of downstream error growth	Persistent source dominance
Model-fidelity metrics	Difference between predicted and measured deviation, update latency, and residual pattern	Trust level of the digital twin	Stable mismatch between model and shop-floor state
Capability metrics	Sigma level, spread stability, tail behavior, defect recurrence	Readiness for release and continuity of control	Capability decline or unstable dispersion
Economic metrics	Rework hours, scrap, inspection burden, maintenance effort	Cost of the current control regime	Rising cost without capability gain
Learning metrics	Repeated escapes, time to isolate the root cause, recurrence of known patterns	Organizational retention of dimensional knowledge	Return of previously corrected failure modes

Table 2 organizes monitoring by the mechanisms that generate deviation, not solely by defect totals. Interface metrics answer whether the build passes. Source metrics answer where to intervene. Model-fidelity metrics answer whether the twin remains trustworthy enough for closed-loop decisions. Economic metrics protect the program from indiscriminate tightening. Learning metrics reveal whether the organization is carrying dimensional knowledge forward or solving the same problem again under a new label.

Aviation programs gain the highest return when they adopt a ranked intervention logic. The program benefits from ranking interfaces by their contribution to functional risk. The upper tier requires tighter tolerance governance, richer metrology, and faster digital updates. Dimensions with lower influence remain under a lighter monitoring regime. This ranked-logic pattern aligns with the engineering approach, where critical hard points were tightened to achieve six sigma, while non-critical hard points were designated for later cost relief. In an aerospace setting,

the same logic supports cleaner trade-offs between reliability, inspection load, and tooling cost.

The broader implication concerns governance culture inside engineering teams. A closed-loop dimensional system requires disciplined alignment between four elements: the deviation source map, the measurement strategy, the twin update rule, and the intervention threshold. Programs that keep those four elements synchronized are more likely to detect amplification early, intervene with precision, and preserve manufacturability without turning every tolerance into a premium requirement.

V. CONCLUSION

Safety-critical aerospace assembly demands a wider understanding of dimensional control than nominal tolerance assignment can provide. Recent studies identify deviation propagation, fixture influence, measurement feedback, and digital synchronization as central to the problem. Local geometric error acquires system significance only through transfer,

amplification, and interaction with real assembly conditions.

Metrology-supported virtual assembly and digital twin calibration form the operational core of Six Sigma control. Once the geometry is measured, the virtual model is updated during production, and tolerance planning stops being a static design exercise and becomes part of a closed decision cycle. That cycle supports earlier diagnosis, sharper intervention, and better alignment between design intent and build reality.

Selective tightening offers the most credible path for implementation. The strongest gains come from ranking critical contributors, tightening them with discipline, and preserving wider tolerance space where contributions to risk remain low. The hypothesis stated in the Introduction is therefore confirmed. Six sigma dimensional control in emerging aviation technologies attains practical engineering value when tolerance allocation, deviation prediction, measurement feedback, and intervention rules are integrated into a single closed-loop framework.

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